L Number	Hits	Search Text	DB	Time stamp
-	27	348/208.2.ccls.	USPAT	2003/08/14 09:31
-	0	348/208.2.ccls. and inclinometer	USPAT	2003/08/13 12:30
-	1	348/208.2.ccls. and attitude	USPAT	2003/08/13 12:31
-	73	348/208.99.ccls.	USPAT	2003/08/13 12:42
-	7	348/208.99.ccls. and attitude	USPAT	2003/08/13 12:41
-	0	348/208.99.ccls. and inclinometer	USPAT	2003/08/13 12:41
-	0	348/208.99.ccls. and inclinometer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 12:42
-	30	348/208.2.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 12:43
-	92	348/208.99.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 12:43
-	92	348/208.99.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 12:43
-	10	348/208.99.ccls. and attitude	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 12:53
-	57	348/208.99.ccls. and fixed	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 12:58
-	16	348/208.99.ccls. and tripod	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 13:02
-	5410	optical adj encoder	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 13:04
-	62	348/$.ccls. and optical adj encoder	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 14:16
-	37	tripod with attitude	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 14:20
-	12	camera and (tripod with attitude)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 14:23

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-	68	camera and (tripod with orientation)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 16:46
-	221	camera and inclinometer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 14:57
-	209	camera and tripod and (pan same tilt)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 15:04
-	127	348/211.99.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 15:05
-	78	348/211.99.ccls. and position	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 15:06
-	24	348/211.99.ccls. and position and angle and sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 16:31
-	2	20030007795.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 15:08
-	2	"20010028237" "20010028237" 20010028237.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 15:09
-	486783	373/&.ccls. and position orientation	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 16:31
-	0	373/&.ccls. and (position orientation)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 16:32
-	1912	373/$.ccls. and (position orientation)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 16:32
-	17	(373/$.ccls. and (position orientation)) and camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 16:33
-	2	(373/$.ccls. and (position orientation)) and tripod	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 16:35
-	499	camera and tripod and (position orientation) and sensor and angle	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 16:48

-	0	camera and tripod and (position orientation) and sensor and angle and @ad<=1991122	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 16:49
-	369	camera and tripod and (position orientation) and sensor and angle and @ad<=19991122	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/13 16:49
-	13	camera and tripod and pan and roll and pitch and tilt and sensor	USPAT	2003/08/14 09:32
-	16	camera and tripod and pan and roll and pitch and tilt and sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/14 10:25
-	0	camera and tripod and pan and roll and pitch and tilt and sensor and optical adj encoder	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/14 10:26
-	140766	(camera and tripod and pan and roll and pitch and tilt and sensor) ans encoder	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/14 10:26
-	6	(camera and tripod and pan and roll and pitch and tilt and sensor) and encoder	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/14 14:09
-	79	camera near1 stabilization	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/14 14:15
-	331	camera with gimbal	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/14 14:16
-	44	(camera with gimbal) and stabilize	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 11:54
-	5	("3813788" | "4158261" | "4973144" | "5237450" | "5868031").PN.	USPAT	2003/08/14 14:18
-	4	("2427130" | "3638502" | "4989466" | "5184521").PN.	USPAT	2003/08/14 14:22
-	33	3638502.URPN.	USPAT	2003/08/14 14:26
-	4	("2427130" | "3638502" | "4989466" | "5184521").PN.	USPAT	2003/08/14 14:27
-	1	5868031.URPN.	USPAT	2003/08/14 14:28
-	33	4033541.URPN.	USPAT	2003/08/14 14:48
-	7	("4033541" | "4052654" | "5067084" | "5075861" | "5124938" | "5169090" | "5172323").PN.	USPAT	2003/08/14 14:56
-	7	("4033541" | "4052654" | "5067084" | "5075861" | "5124938" | "5169090" | "5172323").PN.	USPAT	2003/08/14 14:57
-	33	4033541.URPN.	USPAT	2003/08/14 14:58
-	6	3775656.URPN.	USPAT	2003/08/14 14:59

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-	2	6100925.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 12:08
-	0	wo9510919.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 11:56
-	5	9510919.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 11:56
-	3	inclinometer with attitude with camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 12:10
-	7	(inclinometer with attitude) same camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 12:12
-	16	(inclinometer with movement) and camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 12:14
-	56	(accelerometer with attitude) and camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 12:34
-	8	(sensor with tripod adj1 head) and camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 12:48
-	0	(accelerometer with tripod adj1 head) and camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 12:48
-	1	(accelerometer with tripod) and camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 12:50
-	671	(sensor with attitude) and camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 12:51
-	12	(sensor with attitude) and camera and tripod	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 12:51
-	20522	(sensor with (attitude or orientation or position)) and camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 12:54
-	384	((sensor with (attitude or orientation or position)) and camera) and tripod	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 12:54

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-	36	sensor with (camera adj (attitude))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 14:25
-	467	348/169$.ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 14:27
-	220	348/169$.ccls. and sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 15:50
-	2	4623930.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 15:57
-	2	4713697.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/08/15 15:57